

Road BMP Effectiveness Best Available Science And Research Alternatives

1		
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3		
4	Context	1
5	Statement of the Problem	2
6	Project Objectives	6
7	Critical Questions	7
8	Best Available Science Summary	7
9	Alternative Research Approaches	12
10	References	28

Context

Washington State Forest Practices are regulated by means of the Forest Practices Act (Title 222 WAC) and Forest Practices Rules adopted by the Washington Forest Practices Board (WFPB). The WFPB is charged with developing rules that protect the state’s public resources while maintaining a viable timber industry. Since much of the land regulated under the act contains habitat for aquatic and riparian-dependent species that have been, or may be, listed under the Federal Endangered Species Act (ESA), the Washington Department of Natural Resources (WADNR) has developed a Forest Practices Habitat Conservation Plan (FPHCP) to provide Federal Assurances that the rules will meet the requirements of the ESA.

The WFPB has set up a formal science-based Adaptive Management Program (AMP) to provide technical information and science-based recommendations that will assist the WFPB in determining when it is necessary or advisable to adjust rules and guidance to achieve the Forests & Fish Report resource objectives. The resource objectives are to ensure that forest practices will not significantly impair the capacity of aquatic habitat to: a) support harvestable levels of salmonids; b) support the long-term viability of other covered species; or c) meet or exceed water quality standards, including protection of beneficial uses, narrative and numeric criteria, and anti-degradation (WAC 222-12-045).

The WFPB has empowered the Cooperative Monitoring Evaluation and Research committee (CMER) and the T/F/W Policy Committee (Policy) to participate in the AMP (WAC 222-12-045(2)). In 2012, the WFPB directed CMER to pilot a Lean process for developing a research alternatives document and study design for the Road Prescription-Scale Effectiveness Monitoring Project. Per the new ‘pilot’ process, a Technical Writing and Implementation Group (TWIG) was formed to develop options for addressing questions related to the effectiveness of road prescriptions and best management practices (BMP).

As stated in the 2015 CMER Work Plan, the objectives of monitoring forest roads at the prescription-scale are to:

- 1) Evaluate the effectiveness of road maintenance categories in meeting road performance targets; and
- 2) Identify sensitive situations where prescriptions are not effective.

This project will study surface erosion sediment production and delivery reductions from site-specific BMP.

47
48 It is anticipated the results of this project will inform the forest practices AMP about the
49 effectiveness of BMP in common use, including those used for Road Maintenance and
50 Abandonment Plans (RMAP). These BMP are potentially critical in achieving the FPHCP goals.
51 Should the common BMP used on forest roads prove to be ineffective, Policy and the WFPB
52 may have to revisit the rules and the Forest Practices Board Manual to refine the BMP
53 requirements and application.

54

55 **The Road BMP Effectiveness Project TWIG:**

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57		
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62		
63 Rule Group:	Roads	
64		
65 Rule Context:	WAC 222-24 and Forest Practices Board Manual, Section 3	
66		
67 Research and Monitoring Program	Road Prescription-Scale Effectiveness Monitoring	
68		
69 2016 Budget	\$25,000 (study design development)	

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72 **Statement of the Problem¹**

73 Scientific knowledge of road BMP and prescription effectiveness is insufficient to make sound
74 recommendations. This leads to the potential for:

- 75 1) Landowners wasting money on ineffective treatments;
- 76 2) Rule and BMP implementations being inadequate to achieve functional objectives and
77 performance targets (Schedule L-1);
- 78 3) Overconfidence about the degree of protection landowners can attain (with implications
79 for road construction and maintenance standards); and
- 80 4) Treatments creating additional environmental risks (e.g., landslides and gullies).

81 82 **General Background**

83 Roads play an important role in our society, providing vital links for transportation of people and
84 materials quickly and efficiently. There are hundreds of thousands of miles of roads in
85 Washington State. Many of these roads are unpaved forest roads, used to access lands managed
86 primarily for timber harvest. Forest roads provide many useful functions such as allowing timber
87 products to be transported efficiently to mills, providing access for recreationalists, hunters and
88 fishermen, and even giving wildlife travel corridors.

¹ It should be noted that the statement of the problem, project purpose, and the critical research questions may be refined during the development of the study design.

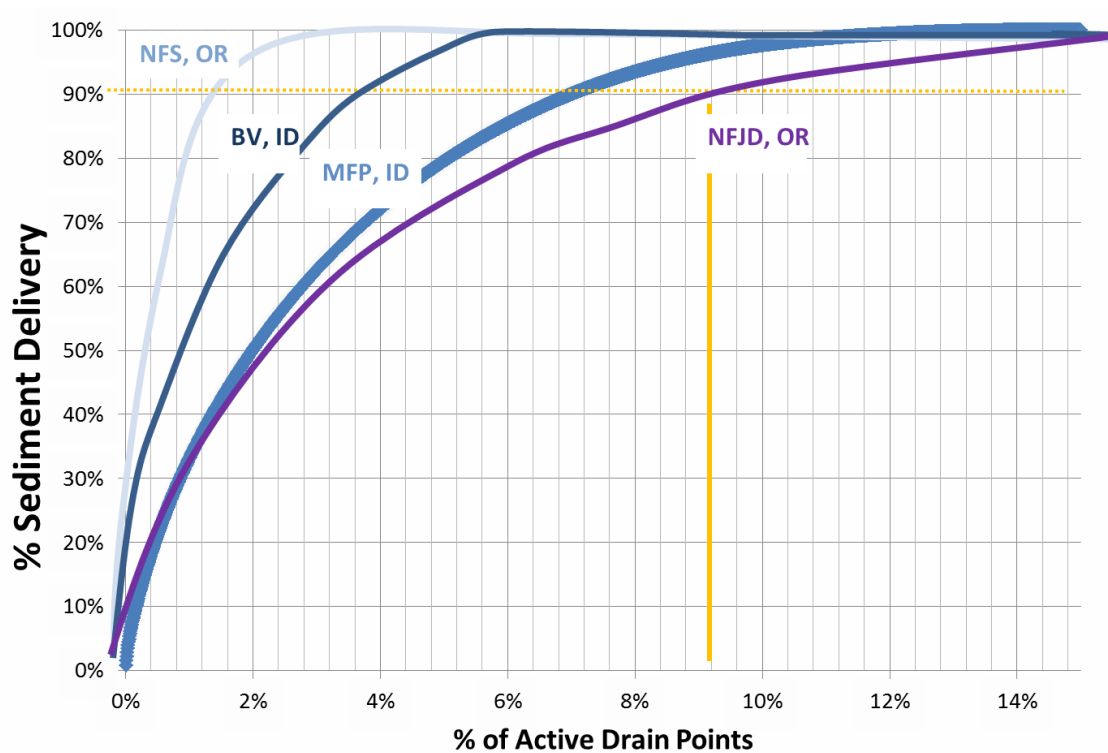
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90 However, roads influence a variety of watershed processes, including sediment production
91 (Megahan and Kidd 1972; Reid and Dunne 1984; Bilby et al. 1989; Luce and Black 1999, 2001a;
92 MacDonald et al. 2001), hydrologic event timing (Wemple et al. 1996; Jones and Grant 1996),
93 and slope stability (Sessions et al. 1987; Montgomery 1994). Of particular concern is road
94 erosion and the locations where it is delivered to streams and rivers. Road erosion can be a large
95 source of anthropogenic sediment in watersheds managed for forest production (Megahan and
96 Kidd 1972; Swanson and Dyrness 1975; Reid and Dunne 1984; Megahan and Ketcheson 1996).
97 The fine-grained sediment produced by road surface erosion has the potential to adversely affect
98 water quality and aquatic resources at the site-scale (e.g., the water quality at a culvert outlet),
99 the reach scale of a channel, and the watershed scale. As noted by Black and Luce (2013):
100 “Forest road runoff and fine sediment delivery are widely acknowledged to have serious impacts
101 on aquatic ecosystems (Cederholm et al. 1981; Platts et al. 1989; Thurow and Burns 1992; Lee et
102 al. 1997; Luce and Wemple 2001).” With rare exception (e.g., Martin 2009 found some square
103 miles of land with forest roads and NO delivery), the potential for adverse effects from forest
104 roads exists across the roaded, forested landscape. As a consequence, water quality regulations
105 and cumulative effects modeling of forest management have frequently focused on forest roads.
106

107 Excessive sedimentation is the most important cause of lotic ecosystem degradation in the
108 United States in terms of stream distance impacted (USEPA 2000). This is a concern to
109 environmental managers because increased inorganic sediment loads alter the natural biotic
110 community (algae, macrophytes, invertebrates and fishes) in streams (Tebo 1955; Cordone and
111 Kelley 1961; Waters 1995; Wood and Armitage 1997; Kaller and Hartman 2004; Suttle et al.
112 2004; Fudge et al. 2008). Increased inorganic sediment loads, beyond quantities or frequencies
113 that occur naturally, can influence the stream biota in a number of ways. Turbidity increased by
114 sediments can reduce stream primary production by reducing photosynthesis, physically
115 abrading algae and other plants, and preventing attachment of autotrophs to substrate surfaces
116 (Van Nieuwenhuysse and LaPerriere 1986; Brookes 1986). Decreasing primary production can
117 affect many other organisms in the stream food web (Izagirre et al. 2009). Sedimentation has
118 been shown to be a major factor in the loss of habitat for mussels worldwide (Poole and
119 Downing 2004; Geist and Auerswald 2007). Minshall (1984) examined the importance of
120 substratum size to aquatic insects and found that substratum is a primary factor influencing the
121 abundance and distribution of aquatic insects. Aquatic macroinvertebrates are adversely affected
122 by habitat reduction and/or habitat change resulting in increased drift, lowered respiration
123 capacity (by physically blocking gill surfaces or lowering dissolved oxygen concentrations), and
124 reducing the efficiency of certain feeding activities especially filter feeding and visual predation
125 (Lemly 1982; Waters 1995; Runde and Hellenthal 2000; Suren and Jowett 2001).
126 Macroinvertebrate grazers are particularly affected as their food supply either is buried under
127 sediments or diluted by increased inorganic sediment load thus increasing search time for food
128 (Suren 2005; Kent and Stelzer 2008). Deposited sediments affect fish directly by smothering
129 eggs in redds (Fudge et al. 2008), altering spawning habitat, and reducing overwintering habitat
130 for fry (Cordone and Kelley 1961), and indirectly by altering invertebrate species composition,
131 thereby decreasing abundance of preferred prey (Suttle et al. 2004). Declines in salamander
132 abundance also were seen with increases in fine sediment inputs (Lowe and Bolger 2002).
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Specific Statement of the Problem

Roads are persistent sources of fine sediment to forest streams, which otherwise have characteristically clear water except during significant storm events. While substantial improvements in water quality have been secured in recent decades through diligent application of mitigation measures (usually called best management practices or “BMP”) for sediment from forest roads, there are still some locations where noticeable loading occurs related to forest roads (Dubé et al. 2010). Recent work has demonstrated that sediment delivery from forest roads is focused in a small fraction of the road network. Two Washington studies found that only 10-11% of the forested road length is delivering sediment to the channel network (Dubé et al. 2010; Martin 2009). Similar work in Oregon and Idaho, summarized in Figure 1, shows that 90% of the delivered sediment comes from 9.2% of the drainage points (Black et al. 2013). That fraction is primarily comprised of larger, more heavily travelled roads in proximity to streams. Mitigation for these locations has proven more challenging than in other places, and better information is needed to hone our capacity to efficiently handle sediment from these high-traffic, near-stream (HTNS) road segments.



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Figure 1: Pareto analysis of sediment production from four GRAIP watershed surveys (Black et al. 2013).

There are several reasons why HTNS road segments are particularly challenging for sediment control. Frequent heavy traffic decreases the effectiveness of surfacing roads with quality rock by the crushing of the rock and pumping of fines from the substrate. Drainage modifications that limit delivery are also compromised when water bars are worn and ruts form (e.g., Burroughs and King 1989; Black et al. 2013). Segments carrying frequent heavy traffic may be the most difficult to restrict traffic on during wet weather, increasing the severity of these effects. These

162 roads also need frequent maintenance of the surface (e.g., frequent grading to reduce pot hole
163 development) to maintain their ability to handle traffic. The close proximity to streams makes it
164 difficult to rely on infiltration into the forest floor to disconnect road discharges from streams.
165 The proximity to streams or stream crossings also means that these roads will be the wettest and
166 most affected by groundwater and exfiltration from the hillslope. In technical parlance, these are
167 high production (detachment of sediment from the road surface and ditch), high delivery (greater
168 fraction of produced sediment carried to stream) road segments.

169
170 These HTNS roads present strong technical challenges. Since excessive fine sediment in fish-
171 bearing streams is perhaps the single largest, management-related factor impacting instream
172 biota, including listed fish species, reducing road surface erosion and delivery to stream is of
173 critical importance. Not only are HTNS roads more likely to deliver sediment to streams, they
174 are typically critical to the transportation network as key mainline roads. Therefore, HTNS roads
175 may warrant additional investment by landowners to use enhanced BMP not only to meet
176 stewardship goals, but for operational needs as well. Improved mitigation for erosion of HTNS
177 forest roads may allow better operational flexibility so forest operations can be conducted in a
178 wider range of weather, with improved vehicle-use capacity and potentially reduced
179 maintenance. However, road upgrades and enhanced BMP are a significant cost; therefore,
180 improved knowledge of individual and in-combination BMP is essential for understanding the
181 return on BMP investments.

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183 Whether from the landowner or regulatory perspective, a central question is what combinations
184 of surfacing, ditch line management, traffic control, and drainage management will most
185 efficiently and effectively mitigate sediment yields and hydraulic effects from HTNS roads? The
186 question pivots on combinations because there is already significant information on what
187 individual treatments such as rocking or traffic changes can do to mitigate sedimentation (e.g., as
188 summarized by Burroughs and King 1989). Such information has been formulated into simple
189 empirical approaches that estimate sediment yield from a road surface based on a number of
190 empirical multipliers similar to the Universal Soil Loss Equation (USLE) (e.g., Dubé et al. 2010;
191 Luce and Black 2001a). These efforts predicate on two assumptions: 1) That the implementation
192 of multiple BMP has the expected positive benefits; and 2) That those positive benefits are
193 multiplicative. Luce and Black (2001a) experimented with BMP combinations and their results
194 do not support these two assumptions.

195
196 BMP treatments are rarely used alone and it is the combination of activities that has been
197 inadequately studied. Some combinations work well together while others may produce little
198 additive improvement at a greater cost. Under certain circumstances, one BMP may even reduce
199 the effectiveness of another one; for example, paving a road reduces production of sediment
200 from the surface, but contributes more water to the ditch line, and if the ditch is bare soil, erosion
201 can increase relative to that expected from a gravel road. Furthermore, safety and operational
202 constraints imposed by one part of a design can impair another part. For example, rocking with
203 high value rock sometimes encourages use of a road grader to retrieve lost rock from the ditch
204 line, which in turn renews the availability of sediment in the ditch (where stream power is high)
205 potentially negating much of the benefit of the rocking.

206

207 Furthermore, these simple models based on empirical, site-specific studies may have very little
208 applicability to locations other than where they were developed (e.g., WARSEM) as they are not
209 process-based representations of the effects of BMP. Therefore, there is a strong need for joint
210 development of extensive field studies and process-based numerical modeling approaches using
211 physical principles to study the effects of single and multiple BMP on water and sediment
212 transport across roads. Models should provide the physical framework for the different pathways
213 of BMP influence on water and sediment flows, while field observations would provide the data
214 to further refine models, and can be used as model input parameters.

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217 **Project Objectives**

218 The forest practices road rules are designed to protect water quality and riparian/aquatic habitats
219 through road prescriptions (WAC 222-24) and best management practices (BMP – Forest
220 Practices Board Manual, Section 3, 2013)². These prescriptions and BMP, also called
221 “treatments” in this document, are broadly intended to minimize: 1) sediment production and
222 delivery from the road prism; 2) hydrologic connection between roads and the stream network;
223 and 3) the risk of road-related landslides caused by inadequately built and maintained roads and
224 culverts. This project will specifically focus on 1) and 2) – it will take a different study design to
225 evaluate the treatment effectiveness of 3).

226

227 Although an extensive body of research of the performance of individual BMP already exists
228 (e.g., as summarized in Burroughs and King 1989 and Dubé et al. 2004), some individual BMP
229 are not well studied and substantial gaps exist in our understanding of the collective performance
230 of road BMP at the site scale in reducing sediment production, sediment delivery and hydrologic
231 connectivity. Of particular concern is that conceptual models used in the design of road BMP
232 field studies in the literature assume a multiplicative approach such that data collection is
233 focused on observing and measuring factors that are used in multiplicative models. This limits
234 the scalability of those observations using different, more process-based models.

235

236 As landowners work to complete implementation of their RMAP and to meet road sediment
237 performance targets and water quality standards, it is important to provide them and other
238 stakeholders with a more confident technical foundation for determining which BMP are most
239 effective and cost effective at minimizing the discharge of sediment to the stream network and
240 the practical and operational limitations of what can be achieved in certain sensitive
241 environmental settings.

242

243 In summary, our understanding of BMP effectiveness is too incomplete to make sound
244 recommendations based on existing scientific evidence. Therefore, we may not be achieving
245 resource objectives, nor applying BMP in the most cost effective manner with the best risk trade-
246 offs.

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253 **Critical Questions**

254 **CMER Work Plan Critical Question**

- 255 • *Are road prescriptions effective at meeting site-scale water quality standards and*
256 *performance targets for sediment and water? (Exclusive of mass wasting prescriptions,*
257 *which are covered in the Unstable Slopes Rule Group.)*
258

259 **Study Design Critical Questions**

- 260 1) How effective are road sediment BMP, individually and in combination, at
261 minimizing production and delivery of coarse and suspended sediments from forest
262 roads to streams?
263
264 2) What is the comparative effectiveness of BMP in minimizing the production, routing,
265 and delivery of sediment to streams? And what are the comparative installation cost
266 effectiveness, and maintenance cost effectiveness and frequency, of these BMP?
267
268 3) Are combinations of individual BMP for the roads and ditches additive,
269 multiplicative, synergistic, or antagonistic?
270
271 4) For individual or combinations of BMP, are increases in turbidity minimized? If
272 turbidity increases, at what stream length below the stream crossing does it abate?
273
274 5) To what extent do road BMP affect water storage and erosion potential at site-scale
275 road segments?
276
277 6) How do different characteristics of topography and lithology effect the selection and
278 design of road BMP?
279
280 7) How quickly after installation or removal of BMP does the post-construction
281 disturbance that temporarily increases sediment production and delivery abate?
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284 **Best Available Science Summary**

285 **Empirical Research**

286 The generation of fine sediment from road networks in the forested environment has been
287 investigated for more than forty years. The largely unpaved road networks are geographically
288 extensive and therefore cross or lie parallel to many streams across the landscape. Early logging
289 limitations led to high road densities; high rainfall in the coastal region causes high stream
290 density and numerous stream crossings and, thus, road impacts are unusually high. In addition,
291 early engineers largely took a pragmatic approach to railroad and road building by placing the
292 larger “mainline roads” along the mainstem of the principal river and the larger tributaries in a
293 watershed. So, it became clear to the early researchers that this juxtaposition had the potential to
294 deliver substantial loads of eroded material to river networks (e.g., Megahan and Kidd 1972;
295 Beschta 1978; Reid and Dunne 1984; Bilby 1985).

296
297 The earliest research was conducted in the 1970’s and 1980’s (e.g., Megahan and Kidd 1972;
298 Reid and Dunne 1984) and served to illuminate how much sediment was being produced from

299 different parts of the road prism under a variety of circumstances. In particular, Walt Megahan
300 and colleagues made numerous contributions to the body of science relating to road prism
301 sediment sources. One of their important contributions was the 1972 effort evaluating the role of
302 subsurface storm flow interception (SSSFF) - SSSFF produced 7.3 times more water than the
303 road's surface; this result fundamentally changed our understanding of roads and their impact on
304 the landscape.

305
306 Subsequent efforts focused on traffic levels (e.g., Luce and Black 2001a and references therein),
307 tread configuration (e.g., Burroughs and King 1989), tread surfacing (e.g., Swift 1984) and
308 cutslope vegetation (e.g., Luce and Black 2001b). The effectiveness of cross-drain spacing has
309 been extensively studied (e.g., Montgomery 1994; Wemple 1996; Croke and Mockler 2001;
310 Luce et al. 2014) as has the benefit of quality rock surfaces (e.g., Foltz and Truebe 1995). It has,
311 in fact, been common to measure sediment production across a variety of situations. Most of this
312 research has focused on the measurement of sediment production or delivery with and without a
313 single BMP application.

314
315 The work by Luce and Black (1999) is particularly important to western Washington because it
316 was conducted in the same ecoregion – the Oregon Coast range. In an intensive study, they
317 examined road design and maintenance at 74 plots where they measured sediment production
318 and road features. Looking at distance from culverts, road slope, soil characteristics, and
319 cutslope height as well as the vegetation condition of cutslopes and ditches, they were able to
320 develop relationships among variables which greatly improve erosion estimates. In both of
321 Megahan and Kidd (1972) and Luce and Black (1999), there was an extensive field program of
322 replicated treatments allowing reasonably powerful statistical tests among site characteristics and
323 treatments. These are only examples of some of the profound work previously completed, but
324 these examples allow us to consider what is still needed, how previously completed work can be
325 built on, and the effort necessary to collect the meaningful data.

326
327 A variety of useful methods for quantifying surface erosion has been described in the literature
328 (Megahan and Kidd 1972; Reid and Dunne 1984; Ice 1986; Bilby et al. 1989; Foltz and Trube
329 1995; Luce and Black 1999; Kahklen 2001; MacDonald et al. 2001 and 2004). This information
330 was briefly summarized in Black and Luce (2013) who point out that “the methods require a
331 range of effort and expense and vary substantially in accuracy.” Black and Luce (2013) provide a
332 settling basin and tipping bucket design that measures both water and sediment discharge for
333 individual road plots which can be systematically applied to road sediment and road hydrology
334 studies in the future.

335
336 The sum of the research had grown enough by the early part of this century that researchers
337 could review the combined findings. In 2004 in a CMER-funded project, Drew Coe did a review
338 of the published literature – 35 studies. The review examined projects that looked at both site and
339 basin level responses. While the individual studies focused on specific topics to meet their
340 project's objectives, the body of the science could be summarized into several key findings.
341 Many researchers documented how site-specific conditions dramatically change runoff
342 processes. A few studies highlighted the importance of the interception of surface flow by
343 cutslopes as a dominant mechanism. The magnitude of that interception is dependent on
344 lithological features. Another theme in the reviewed work was the extent of connectivity

345 between the road and stream network and the factors exerting influence on connectivity. The
346 document also provided insights from studies on the hydrologic effects streams have on runoff
347 generation. Much of this work was the basis of the early generations of road models, particularly
348 another CMER-funded project, WARSEM (Dubé et al. 2004).

349
350 In a subsequent publication, MacDonald and Coe (2008) compared sediment delivery from roads
351 in 11 studies from across the world. The work compared research from across the US and other
352 locales such as New Zealand and the US Virgin Islands with a wide range of estimated
353 production rates both within and between studies. They segregated the studies by road prism
354 feature and were able to estimate sediment production by road surface, and cutslopes and
355 fillslopes. In addition, they compared road erosion fine sediment inputs to landslide delivery of
356 fine sediment. When they scaled the road studies to the work focused on landslides, the values
357 were similar and in some cases larger in the road-related erosion. One difference was that road-
358 related delivery was primarily at stream crossings.

359 360 Model Development

361 Efforts to develop models of road erosion that could be applied at larger scales has resulted in
362 numerous summaries of the existing body of empirical research (e.g., Dubé et al. 2004;
363 MacDonald and Coe 2008). The development of models became imperative as scientists and
364 managers recognized that given the extent of road networks, tools needed to be developed to
365 better understand potential cumulative impacts and how they might prioritize remediation efforts.

366
367 Road erosion models can be grouped into two categories, empirical and physically-based.
368 Empirical models are based on statistically significant relationships between erosional response
369 (road surface, ditch, cutslope) and independent site variables or factors (e.g., geology, road
370 surfacing and length, rainfall). Effects of independent site variables are incorporated as
371 multipliers to predict total erosion from a road segment, which is then multiplied by a sediment
372 delivery ratio (SDR) to estimate sediment delivered to a nearby stream. Empirical models are
373 used to predict mean annual sediment contribution from roads often at the catchment scale.
374 Physically-based models incorporate conservation equations that describe sediment detachment,
375 transport and delivery processes from road segments which are driven by rainfall and overland
376 flow. Models typically share a relatively standard road surface hydrology component for
377 modeling infiltration and runoff generation, driven by rainfall events, although they disregard
378 interception of surface and subsurface flow from hillslopes by roads.

379 380 Empirical Models

381 Washington Department of Natural Resources (WADNR) developed Watershed Analysis
382 methods (WFPB 1995), which included a series of empirical relationships to estimate road
383 surface erosion based on empirical modeling concepts developed by Megahan and Kidd (1972)
384 and Megahan (1974) and the R1-R4 model (Cline et al. 1981; Ketcheson et al. 1999). A number
385 of similar watershed modeling tools that employ different software have evolved from the
386 Watershed Analysis methods of WADNR to assess impacts of roads on annual sediment yields.
387 The models estimate annual road surface, ditch, and cutslope erosion based on multiplicative
388 empirical site-specific factors (geology, surfacing, traffic, rainfall, sediment delivery), sum them
389 up, and multiply by a road age factor. Among these models, Washington Road Surface Erosion
390 Model (WARSEM) was developed as a Microsoft Access database application. Boise Cascade

391 developed a GIS-based program (SEDMODL) to automate the WADNR road erosion
392 calculations used in WARSEM for landowners with extensive road networks. Version 2 of this
393 model (SEDMODL2) was developed by NCASI in collaboration with Boise Cascade (NCASI
394 2003). The model uses an elevation grid combined with road and stream information layers to
395 produce a GIS version of WARSEM. WARSEM and its interface with SEDMODL2 is a
396 spatially distributed model by road segment, including features for estimating ditch, cutslope,
397 and road surface erosion. WARSEM can be applied at large catchment scales and the effects of a
398 variety of Best Management Practices (BMP) enable the model to be used to aid catchment
399 decision-making (Dubé et al. 2004; Fu et al. 2010).

400
401 GRAIP is a distributed watershed-scale tool that analyzes risks from multiple erosion processes
402 for forest roads, including surface erosion, gully, landslides, and stream crossing failure, in a
403 GIS environment based on road inventory and terrain data (Prasad et al. 2005). As input, GRAIP
404 requires GIS coverages of road lines and drain points to represent the continuity of water flow
405 paths along and off of the road. The model uses a base erosion rate (A), scales that with
406 multipliers for topographic factors of flow path length (L) and slope (S), a vegetation factor (V),
407 and a road surface factor (R), and estimates mean annual sediment yield from a watershed,
408 $SY=A*L*S*V*R$ (kg/yr) based on the formula of Luce and Black (1999). Sediment production
409 from road segments can be mapped using GIS. The model uses simple rules to route sediment to
410 drain points such as culverts, estimates sediment delivery to streams from culvert outlets, and
411 routes accumulated sediment from culverts through the channel network. The routed sediment
412 gives a long-term average of sediment yield sourced from road surfaces. Sediment delivery from
413 sub-catchments within a watershed can be analyzed and compared in relation to road density and
414 other factors. GRAIP includes a landslide risk component that estimates an index of stability
415 (SI). SI increases in the model at culvert locations where water concentrates at a point outlet.
416 While the representation of roads in GRAIP is based on an empirical equation which needs a
417 baseline erosion rate, the range of integrated processes represented in GRAIP makes it an
418 effective tool to examine relative impacts of road conditions holistically across a watershed.

419 420 Physically Based Models

421 Two physically based models have been applied to modeling road erosion: WEPP and Kinos. Of these,
422 WEPP has a specific module intended to assist users in inputting parameters for roads. That
423 version – WEPP Road – is limited to modeling road segments (Elliot and Hall 1997). WEPP Road
424 is a fairly generic tool that is run online using site and road conditions selected from a menu
425 of default choices developed largely based on empirical observations. Site conditions include
426 climate (obtained from weather stations), soil textural type, rock cover %, and inputs to
427 characterize road geometry such as gradient, length and width of road, fill and buffer, as well as
428 road design conditions. The Road version does not require any site-specific field observations
429 and, therefore, it is relatively easy to implement and can be used directly from the web
430 (<http://forest.moscowfsl.wsu.edu/fswepp/>). Another interface, WEPP Road Batch, predicts
431 erosion for multiple road segments, currently up to 200 segments in a batch. Both interfaces
432 predict average annual erosion only.

433
434 Site-specific data can be incorporated in the WINDOWS version of the model, which allows
435 users to run both hillslope and ‘watershed’ configurations (Elliot and Hall 1997; Elliot et al.
436 1999a), where the ‘watershed’ configuration allows for using shapes beyond the single-plane

437 representation in WEPP Road. However, the generic WINDOWS version requires a large
438 number of data inputs which are often difficult to obtain in the field and are highly uncertain.
439 WEPP was designed around BMP for farmer's fields, and adaptation to roads has required ad-
440 hoc adjustments to create a road-like simulation. Consequently the web-based version offers a
441 simpler application option for roads. A strong aspect of WEPP is its capacity to develop
442 continuous simulations driven by sequences of rainfall events. While this model can be useful to
443 characterize relative rates of sediment production from different road surfaces for initial design
444 and maintenance purposes, it does not include functionality for road sediment BMP. In addition,
445 the high data intensity makes its implementation difficult and introduces a high degree of
446 uncertainty on model results.

447
448 Another physically-based model that has shown some predictive capability for road erosion is
449 KINEROS2. However this model does not have an explicit road component, and was used in a
450 single study that used a road surface hydrology and sediment yield measurements in Thailand
451 (Ziegler et al. 2001).

452 Model Limitations

453
454 Several studies evaluated and reviewed the performance of empirical and physically-based road
455 models against observations (Elliot et al. 2009; Fu et al. 2010; Dubé et al. 2011). Studies that
456 used WEPP Road have shown varying levels of model performance against observed storm
457 runoff and sediment yields from roads. At different sites, both under (e.g., Peranich 2005) and
458 over estimations (e.g., Amann 2004) of runoff and erosion have been reported in studies that
459 used WEPP Road. Busted (2004) had success with model predictions in large storms, and under
460 predicted response driven by small storms.

461
462 Dubé et al. (2011) compared SEDMODL2/WARSEM, GRAIP, WEPP Road and WEPP
463 watershed models against a large data set of road erosion observations at 9 sites across the US
464 that had sufficient data to run and test the models. The WEPP (PC interface) model which has
465 the ability to predict runoff and erosion from individual storms produced relatively better results
466 for individual storms than for long-term averages. The GRAIP and SEDMODL2 models
467 predicted between-segment variations generally well and were found suitable for relative
468 comparisons of different management conditions. Overall, none of the models showed good
469 performance in predicting actual values of average annual runoff and erosion at all sites. The two
470 main points of the analysis are that the models were reasonably good at discerning relative
471 differences among locations, but poor at predicting actual amounts of sediment delivered. This
472 is both encouraging and disappointing. Encouraging, because they should allow prioritizations
473 of road segments for remediation and possibly be useful in evaluating improvements.
474 Disappointing because with the regulatory process it is necessary to have a reasonable estimate
475 of how much sediment is delivered. Dubé et al. (2011) recommended the use of local data from
476 field observations to calibrate the surface erosion models if estimates of actual values are needed.
477 Therefore, more extensive information could both improve actual modelling estimates in a
478 region and allow enhancements to the model(s).

479
480 In summary, while simple models are thought to be more useful and easily applied for land
481 management purposes, more complex models can conceptually provide a basis for building
482 improved understanding and scientific knowledge. However, both approaches provided in the

483 literature have shown significant deficiencies and have very limited utility especially for
484 evaluating the impact of road BMP. Some of the most pronounced limitations of existing models
485 are:

- 486
- 487 • Empirical models are driven by data and work best in regions where they were
488 developed.
- 489 • Spatial and temporal dynamics in the climate are not included in inputs of empirical
490 models.
- 491 • The effect of each factor on sediment yield is assumed to be multiplicative, following the
492 USLE equation idea, without much physical justification. One publication, Luce and
493 Black (2001a), notes that the multiplicative interaction is in error for independently
494 derived empirical effects of traffic and ditch grading. That documents a need for a better
495 theoretical foundation for mixed BMP effect modeling.
- 496 • Among models, only WARSEM considers the effects of BMP from a list of 70 different
497 BMP choices. In the WARSEM manual, each BMP is described qualitatively and a
498 deterministic multiplier is assigned to introduce the influence of BMP in the calculated
499 sediment yield (Table C-1, WARSEM manual, Dubé et al. 2004). These multipliers were
500 based on very limited data, and were not systematically obtained by holding other
501 conditions constant while changing one BMP. Because multipliers were obtained from
502 limited sites, inference beyond the local setting is not validated. Nor is there a guarantee
503 that one BMP is not redundant with another. The model does not build physical
504 causalities between BMP and the hydrologic and erosional responses of the road setting.
- 505 • The WEPP runoff generation component poorly predicts runoff responses in most data
506 sets collected at a range of study sites as reviewed by Dubé et al. (2011). Natural
507 hydrology of a road site, such as base flow and surface flow contributions to ditches and
508 culverts from hillslopes, was not incorporated in the existing physically-based models for
509 roads.
- 510 • Both physically based models only work on assemblages of planes, so water cannot
511 accumulate in ruts or ditches unless they are explicitly input by the user (they do not exist
512 at all in WEPP Road). Concentrated flow erosion in WEPP is not physically based but
513 essentially input as a parameter by the user. This is an important factor in evaluating rut
514 development and ditch line erosion in forest roads.

515
516

517 **Alternative Research Approaches**

518 **Overview**

519 Alternatives developed by the TWIG show tradeoffs between doing new empirical research or
520 trying to improve existing models with existing data without doing additional empirical research,
521 between concentrating new empirical research on HTNS roads or doing a wider suite of forest
522 road types, and between doing new empirical research with or without a modeling component.
523 Our preferred alternative, #4 below, proposes empirical research focused on HTNS roads with a
524 modeling component. For each of the five alternatives, we provide details about the approach, a
525 list of products, assessment of benefits and limitations, and estimations of relative time and cost.
526

527 This is step 4 in the TWIG process. If Policy approves follow-up work on one or more of the
528 following alternatives, a study design will be developed. The study design will contain detailed
529 methods for site selection and layout, data collection, and analysis.

530
531 The alternatives we propose are:

532
533 Alternative #1 – Empirical Research of BMP on HTNS Roads

534
535 Alternative #2 – Empirical Research of BMP on HTNS and non-HTNS Roads

536
537 Alternative #3 – Utilize Existing Data to Improve Existing, Segment-Scale Models

538
539 Alternative #4 – Do Empirical Research of BMP on HTNS Roads (Alternative #1) and Utilize
540 New and Existing Data to Improve Existing Models

541
542 Alternative #5 – Do Empirical Research of BMP on HTNS and non-HTNS Roads (Alternative
543 #2) and Utilize New and Existing Data to Improve Existing Models

544
545
546 **Discussion of Alternatives**

547 **Alternative #1 – Empirical Research of BMP on HTNS Roads**
548 **Proposal**

549 Alternative #1 comprises measurements of road sediment production from road prisms and
550 delivery below roads. We propose to research road surface erosion by observation and
551 measurement of sediment production from a sample of individual road segments using sediment
552 traps. We propose to research delivery below roads by observing delivery versus non-delivery
553 (success or failure) from a large number of segments. For Alternative #1, we propose to do
554 detailed empirical research on individual BMP and combinations of BMP targeting specifically
555 HTNS roads.

556
557 **Details of Approach**

558 Opportunities to reduce both sediment production and sediment delivery will be studied. Study
559 sites will be placed in 2-4 distinct regions of climate, lithology and topography in Washington
560 State to address relative effectiveness as a function of regional contexts. During the study design
561 phase, the TWIG will identify potential opportunities to evaluate aquatic effects from differing
562 volumes of road inputs while conducting empirical research on BMP.

563
564 The sampling frame for the sediment production field studies will apply a basic conceptual
565 understanding of the physics of sediment detachment and transport from/through the road tread,
566 cutslope, ditch line, and fill slope to facilitate the exploration of the influences of BMP on
567 sediment production and transport in these different domains. Conceptually, the cutslope and
568 tread generate runoff and sediment, which is then fed to the ditch (or a rut) where concentrated
569 flow transports the sediment. The primary sources of water are the components of the road
570 prism with large areas, the tread and cutslope. The tread generates runoff during relatively
571 intense precipitation events (see Luce and Cundy 1992 and 1994; Luce 2004), whereas the
572 cutslopes produce more runoff from long precipitation events or snowmelt in the Pacific

573 Northwest (Luce 2002). Runoff from both of these sources will carry some fine sediment
574 depending on the characteristics of their surfaces and sediment detachment by raindrops and
575 traffic. Runoff from these areas is generally shallow and diffuse in nature, but when that runoff
576 is accumulated along the ditch line or in ruts, it becomes concentrated flow, and the more
577 powerful flowing water can more actively detach sediment where the soil is exposed.
578 Alternatively, a well vegetated ditch can promote settling of fine sediments from the cutslope or
579 tread. We can think about parallel processes when water runs off of a crowned or rutted surface
580 over the fillslope, as well.

581
582 Empirical Research on Sediment Production Reduction

583 The first approach would use sediment trap technology developed by the USFS (Black and Luce,
584 2013 - see Figure 2 below) to test sediment production differences from several plots applying a
585 few prescribed combinations of BMP, as much to demonstrate the effectiveness of a “best”
586 design as to determine how far it is necessary to go to achieve substantial reductions in
587 production.
588



589
590
591 Figure 2: A sediment trap installed below a road segment.
592

593 Testing of BMP combinations will be done for mixed tread, ditch line, and cutslope treatments in
594 a way that isolates tread and cutslope treatment effects from the concentrated flow treatment
595 effects (see Burroughs and King 1989 for examples of individual effects) as well as how the
596 presence or lack of treatment in the concentrated flow road-element can enhance or limit the
597 effectiveness of tread and cutslope treatments. For example, a graded ditch line can undo
598 sediment reductions from the tread simply because the clean water from a paved road can detach
599 sediment from the bare ditch line to satisfy transport capacity (e.g., Luce and Black 2001a).
600 Although the subject has been approached before for a specific combination (e.g., Luce and
601 Black 2001a), it has not been systematically applied toward the particular end of understanding
602 the general effects of multiple BMP.

603
604 The sediment production tests of BMP will ultimately be stratified by geology and climate, but
605 will initially be applied in a single area with relatively consistent base geology and climate. A

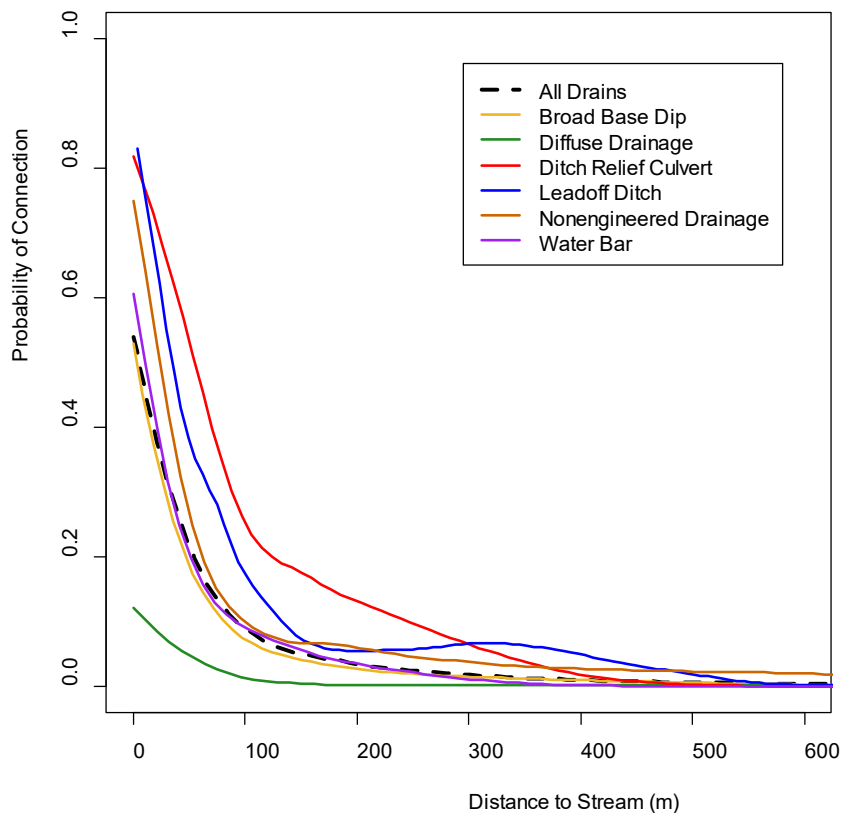
606 sample of about 80 plots was used in the Oregon Coast Range (Tyee Sandstone and weathered
 607 volcanics) in the 1990s using a small crew; it offered a reasonable sample size for a number of
 608 alternative treatment combinations. The number of suitable sites (HTNS) may be the limiting
 609 factor on getting a large sample size; for Alternative #2, obtaining suitable sites for other road
 610 types is not expected to be a limitation.

611

612 Empirical Research on Sediment Delivery Reduction

613 The second approach would use a sediment delivery survey like that used in GRAIP (Black et al.
 614 2012), a simple sampling approach to estimate short-scale delivery reductions when careful
 615 drainage design is applied in these hydrologically challenging locations. The basic question to
 616 address is the relationship of sediment transport distances below drainage features with the
 617 contributing road length/area. Related survey work on stream connectivity shows an effect of
 618 the contributing length or area of road and the probability of delivery at different distances (Luce
 619 et al. 2014, Figure 3). There is also a suggestion from analysis of those data (not shown in
 620 Figure 3) that the effect of distance is more pronounced for smaller contributing areas, which
 621 would be relevant to the use of crowning or water bars to reduce the area of roads contributing to
 622 stream crossings. A few surveys during wet weather conditions may be the most efficient
 623 approach for this study component.

624



625 Figure 3: Probability of hydraulic connection between a road drainage diversion and a stream as
 626 a function of the drain type and distance to stream (Luce et al. 2014).
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Products

- Detailed data about individual and combinations of BMP on HTNS roads in the contexts of lithology and topography.
- An analysis of the data.
- A report about same, including implementation recommendations (i.e., both where and how).

Benefits and Limitations

Alternative #1 will provide information to improve our understanding of road surface erosion and delivery. Doing research across distinct regions of climate, lithology and topography will help develop a better understanding of lithological and topographic controls. That will allow a better understanding of BMP effectiveness for HTNS Roads. In particular, a better understanding of the relationships among BMP and how combinations of BMP relate to each other (e.g., may not be multiplicative as applied in existing operational models). With a focus of HTNS roads, potential gains at the roads most likely to contribute will be evaluated. Not doing research on non-HTNS roads does not mean that these results cannot be applied to non-HTNS roads. Results about lithologic and topographic controls and how BMP interact will be applicable to the rest of the road network, although some special designs for HTNS roads may not be necessary for other road types.

Modeling is a logical extension of empirical research because of the need to apply expensive, detailed, site-specific results to the landscape. NOT doing modeling, as is proposed in Alternative #1, limits the use of these new data and precludes broader landscape application. In particular, local topographic, geologic, and climatological contexts are important. We have gained considerable knowledge from road surface erosion and delivery field studies. Those studies have been conducted throughout the US and elsewhere and, as detailed in Dubé et al. (2011), the field studies have led to the development of models providing reasonably good estimates on relative amounts of material eroded. However, they are only fair to poor in predicting actual amounts of eroded material unless local calibration data are used. Improvement in the existing models is to a large degree limited by available data. Much of the modeling efforts have been using “best available data” which may not be appropriate for many of the road segments where the models may be used (Dubé et al. 2011). Since empirical work cannot be done across all possible scenarios, additional work needs to focus on data collection that will provide the most useful new information to operational prediction of actual amounts. And not proceeding with a modeling effort begs the question: How do we demonstrate meeting WQ standards or TMDL requirements if we don’t model?

While detailed field work is impractical for all roads, a large enough sample size of well replicated treatments across 2-4 regions will improve the inferential capacity of the data set. A primary limitation to gaining more information is the cost associated with such an effort. Treatments will need to be designed to address the various processes and mechanisms for erosion with the treatments and their distribution designed so individual as well as cumulative processes can be quantified. These sampling requirements will drive cost as sites will require both equipment and labor over time. The design will also need substantial site selection effort.

674 Depending on the details of the sampling design, Alternative #1 will answer Critical Questions
675 1-7 for HTNS roads for those specific situations included in the sample (e.g., regions, lithologies,
676 topographic positions) and, to a lesser extent, will answer Critical Questions 1-7 for non-HTNS
677 roads for those specific situations included in the sample. However, extrapolation of these results
678 to other situations and stronger answers to Critical Questions 2-4 and 6 will be possible with
679 modeling (Alternative #4).

680

681 Relative Cost/Time Estimates

- 682 • Mobilization to Each Region – \$4,000
- 683 • Estimate of Site Selection – Unknown
- 684 • Equipment, Installation – \$3,500
- 685 • Monitoring per Site – \$1500 each year
- 686 • Estimate of Number of Sites / Region – 40
- 687 • Estimate of Number of Regions – 2-4
- 688 • Total (minimum estimate) - \$768,000 (assumes only 2 regions; assumes 4 years of
- 689 sampling; does not include site selection and maintenance; could be expanded by using
- 690 results to drive changes to design or factors tested)

691

692 Alternative #1 is approximately 1/3rd the cost of Alternative #2 for the same number of regions,
693 and less than 1/3rd the cost of Alternative #5. It is somewhat less expensive than Alternative #4
694 which proposes an equivalent field effort and incorporates a modeling component. It is much
695 more expensive than Alternative #3.

696

697

698 Alternative #2 – Empirical Research of BMP on HTNS and non-HTNS Roads

699 Proposal

700 Alternative #2 comprises measurements of road sediment production from road prisms and
701 delivery below roads. We propose to research road surface erosion by observation and
702 measurement of sediment production from a sample of individual road segments using sediment
703 traps. We propose to research delivery below roads by observing delivery versus non-delivery
704 (success or failure) from a large number of segments. For Alternative #2, we propose to do
705 detailed empirical research on individual BMP and combinations of BMP on both HTNS roads
706 and other forest roads.

707

708 Details of Approach

709 See above in Alternative #1 – research efforts would be extended to additional road types, but
710 techniques would be the same. The minimum cost estimate has tripled (see below) because three
711 traffic levels would be sampled in each region.

712

713 Products

- 714 • Detailed data about individual and combinations of BMP on both HTNS roads and other
- 715 forest roads in the contexts of lithology and topography.
- 716 • An analysis of the data.
- 717 • A report about same, including implementation recommendations (i.e., both where and
- 718 how).

719

720 Benefits and Limitations

721 Alternative #2 will provide information to improve our understanding of road surface erosion
722 and delivery. Doing research across distinct regions of climate, lithology and topography will
723 help develop a better understanding of lithological and topographic controls. As with Alternative
724 #1, this alternative will improve our understanding of BMP effectiveness for HTNS Roads. Of
725 particular importance in both Alternative #1 and #2, we will develop a better understanding of
726 the relationships among BMP and how combinations of BMP relate to each other (e.g., may not
727 be multiplicative as applied in existing operational models). Doing both HTNS and non-HTNS
728 roads would incrementally improve our knowledge of the entire road network (i.e., relative
729 sediment production and delivery between road types).

730
731 Modeling is a logical extension of empirical research because of the need to apply expensive,
732 detailed, site-specific results to the landscape. NOT doing modeling, as is proposed in
733 Alternative #2, limits the use of these new data and precludes broader landscape application. In
734 particular, local topographic, geologic, and climatological contexts are important. We have
735 gained considerable knowledge from road surface erosion and delivery field studies. Those
736 studies have been conducted throughout the US and elsewhere and, as detailed in Dubé et al.
737 (2011), the field studies have led to the development of models providing reasonably good
738 estimates on relative amounts of material eroded. However, they are only fair to poor in
739 predicting actual amounts of eroded material unless local calibration data are used. Improvement
740 in the existing models is to a large degree limited by available data. Much of the modeling
741 efforts have been using “best available data” which may not be appropriate for many of the road
742 segments where the models may be used (Dubé et al. 2011). Since empirical work cannot be
743 done across all possible scenarios, additional work needs to focus on data collection that will
744 provide the most useful new information to operational prediction of actual amounts. And not
745 proceeding with a modeling effort begs the question: How do we demonstrate meeting WQ
746 standards or TMDL requirements if we don’t model?

747
748 While detailed field work is impractical for all roads, a large enough sample size of well
749 replicated treatments across 2-4 regions will improve the inferential capacity of the data set. A
750 primary limitation to gaining more information is the cost associated with such an effort.
751 Treatments will need to be designed to address the various processes and mechanisms for erosion
752 with the treatments and their distribution designed so individual as well as cumulative processes
753 can be quantified. These sampling requirements will drive cost as sites will require both
754 equipment and labor over time. The design will also need substantial site selection effort.

755
756 Depending on the details of the sampling design, Alternative #2 will answer Critical Questions
757 1-7 for HTNS roads and for other traffic levels for those specific situations included in the
758 sample (e.g., regions, lithologies, topographic positions). However, extrapolation of these results
759 to other situations and stronger answers to Critical Questions 2-4 and 6 will be possible with
760 modeling (Alternative #4).

761 Relative Cost/Time Estimates

- 762 • Mobilization to Each Region – \$4,000
- 763 • Estimate of Site Selection – Unknown
- 764 • Equipment, Installation per Site – \$3,500
- 765

- 766 • Monitoring per Site – \$1500 each year
- 767 • Estimate of Number of Sites / Region – 120
- 768 • Estimate of Number of Regions – 2-4
- 769 • Total (minimum estimate) - \$2,304,000 (assumes only 2 regions; assumes 4 years of
- 770 sampling; does not include site selection and maintenance; could be expanded by using
- 771 results to drive changes to design or factors tested)
- 772

773 Alternative #2 is approximately three times the cost of Alternative #1 for the same number of
774 regions, and almost three times the cost of Alternative #4. It is somewhat less expensive than
775 Alternative #5 which proposes an equivalent field effort and incorporates a modeling component.
776 It is much, much more expensive than Alternative #3.

777 Alternative #3 – Utilize Existing Data to Improve Existing, Segment-Scale Models

778 Proposal

779 We present a modest proposal to apply a geomorphic model to understand road prism erosion in
780 the context of multiple contributing and transporting elements. The proposed model is not
781 intended as an operational tool, rather as a theoretical support tool to place new and existing
782 empirical information into a context that can better be incorporated into the existing operation
783 tools such as WARSEM and GRAIP. This model will be developed at the scale of road
784 segments, and it will include the hillslope hydrologic processes that contribute to road cutslopes.
785 While the model will be capable of predicting water and sediment dynamics in the road prism
786 (tread, cutslope, ditches, and fillslope) under the influence of single and combined BMP, it will
787 also provide capability to conceptually interface with existing operational empirical models to
788 extrapolate their estimates to different environments (topography, lithology, soils) and time
789 scales.
790
791

792 Details of Approach

793 Substantial modeling capacity of road erosion already exists. A review of models available for
794 road erosion estimation is provided above in the Best Available Science Summary. However,
795 these models do not provide a robust theoretical framework to merge information from multiple
796 empirical studies done in different environments. There is no existing model that embodies the
797 necessary features to study the impacts of road BMP alternatives. Empirical models focus on
798 mean annual response using simple linear equations based on multipliers and neglect physical
799 processes, nonlinearity, and climatic variability, while physical models are often over
800 parameterized, adapted from agricultural literature. Representation of hillslope hydrology and
801 lithologic and topographic controls on runoff generation are not included in any model. Models
802 lack proper representations of the continuum of water and sediment generation, transport and
803 storage dynamics across the road prism and the influence of BMP on these processes.
804

805
806 We propose a model to contextually place and extend existing and planned empirical studies into
807 a valid framework for applications using combinations of BMP in operational models like
808 WARSEM or GRAIP. Existing physically based models are too constrained in topology and
809 hydrology to reasonably represent many road BMP. However, a combination of existing
810 software applications can lead to a theoretically rigorous tool to evaluate combinations of BMP

811 and design smaller empirical studies to provide local calibration parameters for physically-based
812 relationships.

813
814 We envision a modular and component-based numerical model that can be used to investigate
815 the effectiveness of individual and collective uses of a range of forest road BMP within road
816 segments integrated to watershed flow paths. A new landscape modeling framework called
817 Landlab is suitable for this purpose (<http://landlab.readthedocs.org/en/latest/index.html>). Landlab
818 is a Python software package that supports numerical modeling in earth science, and especially
819 those fields that deal with earth-surface dynamics including geomorphology, hydrology,
820 glaciology, stratigraphy, and related areas. Landlab is actively being developed by collaborations
821 among University of Colorado, University of Washington (Istanbuluoglu), and Tulane
822 University.

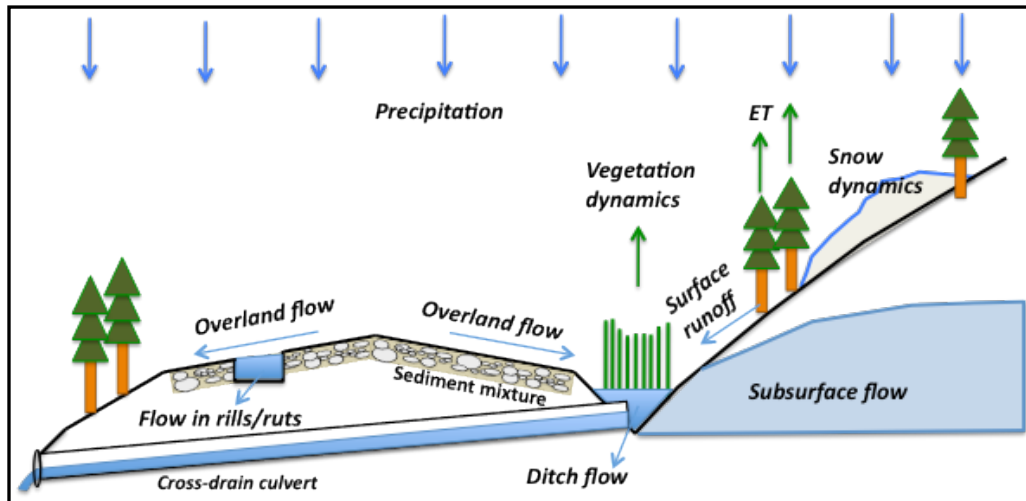
823
824 Landlab is a modeling environment in which scientist can build a numerical landscape model
825 without having to code all of the individual parts (e.g., Tucker et al., 2015). Landlab provides
826 four main resources and capabilities:

- 827
828 1) A library of *code resources* for building two-dimensional numerical models from scratch.
829 The Landlab library includes a powerful “gridding engine” for creating, managing, and
830 iteratively updating data on structured or unstructured grids. The library also includes
831 support for input and output, including input of digital elevation models (DEM) in
832 ArcInfo ASCII format, handling of parameter inputs using formatted text files, and
833 netCDF-format input and output.
834 2) A set of pre-built *components*, each of which implements a numerical representation of a
835 particular process.
836 3) A *framework for building models* by assembling and linking process components.
837 4) A *library of models* that have already been created from component(s).

838
839 In this project we would use Landlab functionalities of spatial representation of model domains
840 and flow generation and routing. Our modeling efforts would initially focus on processes within
841 a road segment while representing incoming flows of water and sediment from the defined
842 boundaries of the road segment (i.e., hillslope contribution and flows from upslope road
843 segments) as external inputs from other models, linking models, or as specified contexts. Such a
844 model will support the planning of experimental field studies by means of developing what-if
845 scenarios and hypothesis testing of BMP design alternatives to note where results of a given
846 empirical study likely depend strongly on other contexts; this powerful model result is only
847 realized by this project if one of Alternatives #4 or #5 is chosen.

848
849 Representation of hillslope hydrology and long-term (seasonal to annual) hydrologic memory is
850 critical in the PNW to obtain realistic hillslope runoff contribution into ditches. For this purpose
851 we would delineate catchment areas that contribute flows into a road segment and use a separate
852 hydrology model to represent hydrological dynamics on slopes (see Figure 4). We envision using
853 an existing watershed hydrology model suitable for the PNW conditions, such as the Distributed
854 Hydrology Soil Vegetation Model (DHSVM) (Wigmosta et al., 1994), and feed off-line DHSVM
855 predictions as input to the road model. The watershed model predictions will provide surface

856 runoff and subsurface flow input in the upper boundary of a road cutslope over sub-daily or daily
 857 time scales throughout simulations.
 858



859
 860
 861
 862 Figure 4. Forest road cross-section with some of the proposed model components indicated in
 863 text.
 864

865 Rainfall-driven infiltration, runoff generation and overland flow routing will be represented on
 866 the road surface, ditches and cutslopes, following the model of Luce and Cundy (1994).
 867 Overland flow will be routed as diffused or concentrated depending on the flow lines dictated by
 868 the surface topography. In the ditches, flow will always be in the form of channel flow. The
 869 model will be built to allow for sediment detachment, transport, and deposition using fixed and
 870 dynamic grid representations. The latter will deform the initial elevation field as rills form.
 871 Because runoff erosion is highly nonlinear to concentrated discharge, representation of surface
 872 dynamics will improve predictions. Routing flows on the road surface will show the implications
 873 of the evolving nature of road surface on the contribution of runoff overland flow on fillslopes.
 874 In the ditch slopes, we will also represent the influence of vegetation (e.g., grass, shrub, bush,
 875 etc.) on flow depth, velocity, shear stress, detachment and transport. Storm processes will be
 876 modeled in hourly or sub hourly time scales, which will depend on model stability conditions
 877 and intensity of rainfall input. Such short time scales will allow developing hydrographs at
 878 culvert outlets and ditches. Continuous hydrological processes will be simulated on contributing
 879 cutslopes at daily or sub daily time scales as needed. Model forcing can be obtained from
 880 gridded climate data used for regional hydrologic models (e.g., Livneh et al. 2013) or local
 881 weather stations as available.
 882

883 Each BMP will be coded as an individual module. BMP will be geographically placed on the
 884 desired location on the road surface, cutslopes, ditches or fillslopes, and will use flows of water
 885 and sediment as inputs. Storage dynamics of water and sediment will be represented in each
 886 BMP, and BMP will provide outflows at their outlets (either point or as continuous boundary).
 887 The modular structure of the proposed model will allow testing of BMP off-line of the road
 888 model, using necessary inputs and outputs as time series. When multiple BMP are used, the
 889 influence of each BMP on runoff and sediment discharge and storage will be linked along the

890 flow paths of integrated hillslope and road prism domains. All BMP will provide outputs to the
891 road segment. Simulations using a combination of BMP will illustrate their cumulative effects on
892 or downstream of the road prism.

893

894 Products

895 This project will deliver a forest roads BMP component in Landlab with applications and a
896 users' manual. The tools will be made available to public through the Landlab web-based model
897 repository (<http://landlab.readthedocs.org/en/latest/>).

898

899 Benefits and Limitations

900 The proposed modeling approaches in Alternative #3 may be able to improve our use and
901 interpretation of existing data sets and thereby lead to better understanding of road surface
902 erosion and delivery. For example, using improved DEM, considering hillslope hydrology
903 above road cutslopes in HTNS roads, and forcing the road surface processes with actual
904 climatologic input will lead to improved interpretation of existing data and models.

905

906 An important advantage of using the Landlab modeling framework in this project will be that the
907 proposed forest roads component will be readily compatible with other processes in Landlab,
908 such as landslides, and hillslope and stream erosion and transport processes. This will facilitate
909 watershed and regional scale evaluations of the impacts of roads on watershed hydrologic and
910 geomorphic processes and the potential improvements that can be achieved by road BMP.

911

912 There will be a number critical limitations of developing new model components without new
913 field studies designed consistent with model theory. Several important drawbacks in relying only
914 on existing data will include differences and inconsistencies in the qualitative and quantitative
915 data and descriptions of site conditions such as climate, topography and lithology, as well as
916 differences in data collection methods and instrumentation among sites. As models become more
917 process-based there is a need for detailed characterization of experimental conditions at field
918 sites where models are evaluated, and have a good representation of model forcing conditions as
919 well as hillslope hydrology. Lack of empirical data systematically collected by focusing single
920 and collective effects of BMP over similar space and time scales would hamper the level of
921 fundamental understanding that can be achieved from this modeling effort.

922

923 Relative Cost/Time Estimates

- 924 • Estimated Cost of Literature Review for Existing Data, gathering data in different
925 formats and geo-referencing the data – \$25,000
- 926 • Estimated Cost of Model Development – \$ 300,000 (assumes 3 years of graduate student
927 time)

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Alternative #4 – Do Empirical Research of BMP on HTNS Roads (Alternative #1) and Utilize New and Existing Data to Improve Existing Models (preferred alternative of the TWIG)

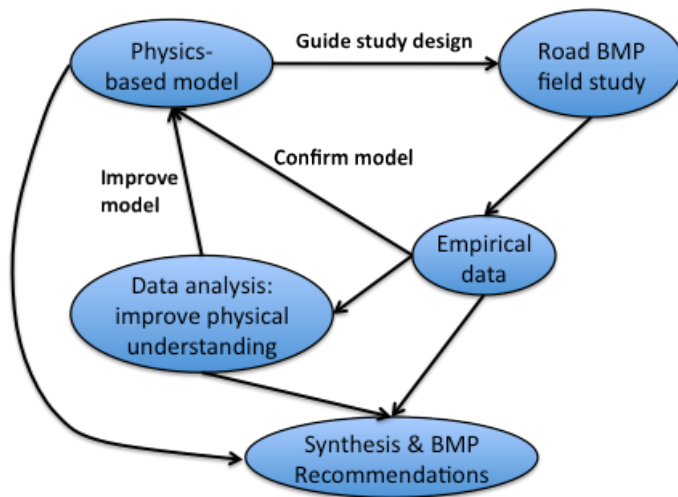
Proposal

Alternative #4 will combine Alternatives #1 and #3 and synthesize co-developed data from field observations and model applications to recommend regional BMP alternatives and suggest approximate relative changes in sediment and water yield predictions in space and time.

Details of Approach

See above in Alternative #1 for details of the proposed field work on HTNS roads. For the remainder of this section, we present this alternative from the perspective of combined field and modeling effort.

The road surface model inter-comparison study of Dubé et al. (2011) showed large uncertainties in model predictions and suggested that most models can only be used at best for relative comparisons of model scenarios for decision making. Among the models they used, only WARSEM included an empirical BMP component. Datasets obtained from field measurements used to develop and evaluate such models focused on quantifying the effects of single BMP at a time and, therefore, are not suitable for testing and evaluating models that can simulate multiple BMP. There is need for developing a theoretical modeling framework for road hydrology and sediment yield modeling with functionality for BMP which could guide the design of empirical field studies in different regions; those results could then be used improve model theory. Figure 5 below illustrates how a theoretical model and fieldwork design can be used in a feed-back loop to improve our understanding of road BMP effectiveness in a region and develop targeted recommendations for stakeholders.



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Figure 5. Conceptual framework to improve understanding of the effects of road BMP through the feedback loop of physically-based modeling, field work design, empirical measurements and use of field data.

963 For example, the model we outlined in Alternative #3 can aid in the planning of field
964 instrumentation, such as sediment traps and flow measurement, by providing runoff hydrographs
965 with estimated contributions of hillslope runoff, subsurface flow and road surface runoff.
966 Preliminary model runs showing active erosion and deposition areas can be used for identifying
967 monitoring sites. Field data will also be used to: 1) Identify the relative roles of local (road
968 features and design) and global (lithology and geomorphology of contributing areas) controls at a
969 field site; 2) Reevaluate model conceptualization and theory to improve the representations of
970 such controls; 3) Update model parameter values; 4) Regionalize model performance; and 5)
971 Identify model limitations in relation to local and global controls. At each field site, other
972 existing modeling tools will be evaluated as potentials for improving existing tools, and
973 interfacing them with Landlab will be considered. In the final year of the project, field data and
974 modeling at all sites will be synthesized, and BMP recommendations will be developed in
975 different regions and with examples of model implementation. We expect that this modeling
976 tool, based on a component-based Landlab landscape modeling framework, can dramatically
977 reduce model coding and development time and costs for future improvements. A graphical user
978 interface (GUI) can be developed in the future to facilitate both research and operational use of
979 the modeling framework.

980

981 Products

- 982 • Detailed data about individual and combinations of BMP on HTNS roads in the contexts
983 of lithology and topography.
- 984 • An analysis of the data.
- 985 • A report about same, including implementation recommendations (i.e., both where and
986 how).
- 987 • This project will deliver a forest roads BMP component in Landlab with applications and
988 a users' manual. The tools will be made available to public through the Landlab web-
989 based model repository (<http://landlab.readthedocs.org/en/latest/>).

990

991 Benefits and Limitations

992 Alternative #4 will provide information to improve our understanding of road surface erosion
993 and delivery. Doing research across distinct regions of climate, lithology and topography will
994 help develop a better understanding of lithological and topographic controls. That will allow a
995 better understanding of BMP effectiveness for HTNS Roads. In particular, a better
996 understanding of the relationships among BMP and how combinations of BMP relate to each
997 other (e.g., may not be multiplicative as applied in existing operational models). With a focus of
998 HTNS roads, potential gains at the roads most likely to contribute will be evaluated. Not doing
999 research on non-HTNS roads does not mean that these results cannot be applied to non-HTNS
1000 roads. Results about lithologic and topographic controls and how BMP interact will be applicable
1001 to the rest of the road network, although some special designs for HTNS roads may not be
1002 necessary for other road types.

1003

1004 Modeling is a logical extension of empirical research because of the need to apply expensive,
1005 detailed, site-specific results to the landscape. In particular, local topographic, geologic, and
1006 climatological contexts are important. We have gained considerable knowledge from road
1007 surface erosion and delivery field studies. Those studies have been conducted throughout the US
1008 and elsewhere and, as detailed in Dubé et al. (2011), the field studies have led to the

1009 development of models providing reasonably good estimates on relative amounts of material
1010 eroded. However, they are only fair to poor in predicting actual amounts of eroded material
1011 unless local calibration data are used. Improvement in the existing models is to a large degree
1012 limited by available data. Much of the modeling efforts have been using “best available data”
1013 which may not be appropriate for many of the road segments where the models may be used
1014 (Dubé et al. 2011). Since empirical work cannot be done across all possible scenarios, additional
1015 work needs to focus on data collection that will provide the most useful new information to
1016 operational prediction of actual amounts.

1017
1018 While detailed field work is impractical for all roads, a large enough sample size of well
1019 replicated treatments across 2-4 regions will improve the inferential capacity of the data set. A
1020 primary limitation to gaining more information is the cost associated with such an effort.
1021 Treatments will need to be designed to address the various processes and mechanisms for erosion
1022 with the treatments and their distribution designed so individual as well as cumulative processes
1023 can be quantified. These sampling requirements will drive cost as sites will require both
1024 equipment and labor over time. The design will also need substantial site selection effort.

1025
1026 Depending on the details of the sampling design, Alternative #4 will answer Critical Questions
1027 1-7 for HTNS roads for those specific situations included in the sample (e.g., regions, lithologies,
1028 topographic positions) and, to a lesser extent, will answer Critical Questions 1-7 for non-HTNS
1029 roads for those specific situations included in the sample. Extrapolation of these results to other
1030 situations and stronger answers to Critical Questions 2-4 and 6 will be possible with the
1031 modeling effort proposed in this alternative.

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1033 Relative Cost/Time Estimates

- 1034 • Alternative # 3 Lit Review and Modeling Effort for Existing Data – \$325,000
- 1035 • Additional Modeling Efforts for New Data, Data Analysis and Synthesis – \$100,000
1036 (assumes another year of graduate student time)
- 1037 • Mobilization to Each Region – \$4,000
- 1038 • Estimate of Site Selection – Unknown
- 1039 • Equipment, Installation – \$3,500
- 1040 • Monitoring per Site – \$1500 each year
- 1041 • Estimate of Number of Sites / Region – 40
- 1042 • Estimate of Number of Regions – 2-4
- 1043 • Total (minimum estimate) - \$1,193,000 (assumes only 2 regions; assumes 4 years of
1044 sampling; does not include site selection and maintenance; could be expanded by using
1045 results to drive changes to design or factors tested)

1046

1047 Alternative #4 is approximately 1/3rd the cost of Alternative #5 for the same number of regions.
1048 It is approximately the cost of Alternatives #1 and #3 combined because it is the combination of
1049 those two alternatives. It is much more expensive than Alternative #3.

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Alternative #5 – Do Empirical Research of BMP on HTNS and non-HTNS Roads (Alternative #2) and Utilize New and Existing Data to Improve Existing Models

Proposal

Alternative #5 will combine Alternatives #2 and #3 and synthesize co-developed data from field observations and model applications to recommend regional BMP alternatives and suggest approximate relative changes in sediment and water yield predictions in space and time.

Details of Approach

Details of the field sampling are discussed above in Alternative #1; this alternative also samples non-HTNS roads as discussed in Alternative #2. Modeling efforts are described in Alternative #3 and the power of combining field and modeling efforts is described in Alternative #4.

Products

- Detailed data about individual and combinations of BMP on both HTNS roads and other forest roads in the contexts of lithology and topography.
- An analysis of the data.
- A report about same, including implementation recommendations (i.e., both where and how).
- This project will deliver a forest roads BMP component in Landlab with applications and a users’ manual. The tools will be made available to public through the Landlab web-based model repository (<http://landlab.readthedocs.org/en/latest/>).

Benefits and Limitations

Alternative #5 will provide information to improve our understanding of road surface erosion and delivery. Doing research across distinct regions of climate, lithology and topography will help develop a better understanding of lithological and topographic controls. That will allow a better understanding of BMP effectiveness for HTNS roads and for other traffic levels. In particular, a better understanding of the relationships among BMP and how combinations of BMP relate to each other (e.g., may not be multiplicative as applied in existing operational models).

Modeling is a logical extension of empirical research because of the need to apply expensive, detailed, site-specific results to the landscape. In particular, local topographic, geologic, and climatological contexts are important. We have gained considerable knowledge from road surface erosion and delivery field studies. Those studies have been conducted throughout the US and elsewhere and, as detailed in Dubé et al. (2011), the field studies have led to the development of models providing reasonably good estimates on relative amounts of material eroded. However, they are only fair to poor in predicting actual amounts of eroded material unless local calibration data are used. Improvement in the existing models is to a large degree limited by available data. Much of the modeling efforts have been using “best available data” which may not be appropriate for many of the road segments where the models may be used (Dubé et al. 2011). Since empirical work cannot be done across all possible scenarios, additional work needs to focus on data collection that will provide the most useful new information to operational prediction of actual amounts.

1097 While detailed field work is impractical for all roads, a large enough sample size of well
1098 replicated treatments across 2-4 regions will improve the inferential capacity of the data set. A
1099 primary limitation to gaining more information is the cost associated with such an effort.
1100 Treatments will need to be designed to address the various processes and mechanisms for erosion
1101 with the treatments and their distribution designed so individual as well as cumulative processes
1102 can be quantified. These sampling requirements will drive cost as sites will require both
1103 equipment and labor over time. The design will also need substantial site selection effort.
1104

1105 Depending on the details of the sampling design, Alternative #5 will answer Critical Questions
1106 1-7 for HTNS roads and for other traffic levels for those specific situations included in the
1107 sample (e.g., regions, lithologies, topographic positions). Stronger answers to Critical Questions
1108 2-4 and 6 will be possible with the modeling effort proposed in this alternative.
1109

1110 Relative Cost/Time Estimates

- 1111 • Alternative # 3 Lit Review and Modeling Effort for Existing Data – \$325,000
- 1112 • Additional Modeling Efforts for New Data – \$100,000+ (expect more \$ than for
1113 Alternative #4)
- 1114 • Mobilization to Each Region – \$4,000
- 1115 • Estimate of Site Selection – Unknown
- 1116 • Equipment, Installation per Site – \$3,500
- 1117 • Monitoring per Site – \$1500 each year
- 1118 • Estimate of Number of Sites / Region – 120
- 1119 • Estimate of Number of Regions – 2-4
- 1120 • Total (minimum estimate) - \$2,729,000 (assumes only 2 regions; assumes 4 years of
1121 sampling; does not include site selection and maintenance; could be expanded by using
1122 results to drive changes to design or factors tested)

1123
1124 Alternative #5 is approximately three times the cost of Alternative #4 for the same number of
1125 regions. It is approximately the cost of Alternatives #2 and #3 combined because it is the
1126 combination of those two alternatives. It is much, much more expensive than Alternative #3.

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